Contents

Dedication v

Preface vii

Editors xi

Contributors xiii

Contents xv

I General Methods in Knowledge Representation and Reasoning 1

1 Knowledge Representation and Classical Logic 3
Vladimir Lifschitz, Leora Morgenstern and David Plaisted

1.1 Knowledge Representation and Classical Logic 3
1.2 Syntax, Semantics and Natural Deduction 4
1.2.1 Propositional Logic 4
1.2.2 First-Order Logic 8
1.2.3 Second-Order Logic 16
1.3 Automated Theorem Proving 18
1.3.1 Resolution in the Propositional Calculus 22
1.3.2 First-Order Proof Systems 25
1.3.3 Equality 37
1.3.4 Term Rewriting Systems 43
1.3.5 Confluence and Termination Properties 46
1.3.6 Equational Rewriting 50
1.3.7 Other Logics 55
1.4 Applications of Automated Theorem Provers 58
1.4.1 Applications Involving Human Intervention 59
1.4.2 Non-Interactive KR Applications of Automated Theorem Provers 61
1.4.3 Exploiting Structure 64
1.4.4 Prolog 65
1.5 Suitability of Logic for Knowledge Representation 67
1.5.1 Anti-logicist Arguments and Responses 67

Acknowledgements 74
Bibliography 74

2 Satisfiability Solvers **89**
Carla P. Gomes, Henry Kautz, Ashish Sabharwal and Bart Selman
2.1 Definitions and Notation 91
2.2 SAT Solver Technology—Complete Methods 92
2.2.1 The DPLL Procedure 92
2.2.2 Key Features of Modern DPLL-Based SAT Solvers 93
2.2.3 Clause Learning and Iterative DPLL 95
2.2.4 A Proof Complexity Perspective 100
2.2.5 Symmetry Breaking 104
2.3 SAT Solver Technology—Incomplete Methods 107
2.3.1 The Phase Transition Phenomenon in Random k-SAT 109
2.3.2 A New Technique for Random k-SAT: Survey Propagation . 111
2.4 Runtime Variance and Problem Structure 112
2.4.1 Fat and Heavy Tailed Behavior 113
2.4.2 Backdoors 113
2.4.3 Restarts 115
2.5 Beyond SAT: Quantified Boolean Formulas and Model Counting . . 117
2.5.1 QBF Reasoning 117
2.5.2 Model Counting 120
Bibliography 122

3 Description Logics **135**
Franz Baader, Ian Horrocks and Ulrike Sattler
3.1 Introduction 135
3.2 A Basic DL and its Extensions 139
3.2.1 Syntax and Semantics of $\mathcal{ALC}$ 140
3.2.2 Important Inference Problems 141
3.2.3 Important Extensions to $\mathcal{ALC}$ 142
3.3 Relationships with other Formalisms 144
3.3.1 DLs and Predicate Logic 144
3.3.2 DLs and Modal Logic 145
3.4 Tableau Based Reasoning Techniques 146
3.4.1 A Tableau Algorithm for $\mathcal{ALC}$ 146
3.4.2 Implementation and Optimization Techniques 150
3.5 Complexity 151
3.5.1 $\mathcal{ALC}$ ABox Consistency is PSpace-complete 151
3.5.2 Adding General TBoxes Results in ExpTime-Hardness . . . 154
3.5.3 The Effect of other Constructors 154
3.6 Other Reasoning Techniques 155
3.6.1 The Automata Based Approach 156
3.6.2 Structural Approaches 161
3.7 DLs in Ontology Language Applications 166
3.7.1 The OWL Ontology Language 166
3.7.2 OWL Tools and Applications 167

3.8 Further Reading 168
Bibliography 169

4 Constraint Programming **181**
Francesca Rossi, Peter van Beek and Toby Walsh
4.1 Introduction 181
4.2 Constraint Propagation 182
4.2.1 Local Consistency 183
4.2.2 Global Constraints 183
4.3 Search 184
4.3.1 Backtracking Search 184
4.3.2 Local Search 187
4.3.3 Hybrid Methods 188
4.4 Tractability 189
4.4.1 Tractable Constraint Languages 189
4.4.2 Tractable Constraint Graphs 191
4.5 Modeling 191
4.5.1 CP $\vee \neg$ CP 192
4.5.2 Viewpoints 192
4.5.3 Symmetry 193
4.6 Soft Constraints and Optimization 193
4.6.1 Modeling Soft Constraints 194
4.6.2 Searching for the Best Solution 195
4.6.3 Inference in Soft Constraints 195
4.7 Constraint Logic Programming 197
4.7.1 Logic Programs 197
4.7.2 Constraint Logic Programs 198
4.7.3 LP and CLP Languages 198
4.7.4 Other Programming Paradigms 199
4.8 Beyond Finite Domains 199
4.8.1 Intervals 199
4.8.2 Temporal Problems 200
4.8.3 Sets and other Datatypes 200
4.9 Distributed Constraint Programming 201
4.10 Application Areas 202
4.11 Conclusions 203
Bibliography 203

5 Conceptual Graphs **213**
John F. Sowa
5.1 From Existential Graphs to Conceptual Graphs 213
5.2 Common Logic 217
5.3 Reasoning with Graphs 223
5.4 Propositions, Situations, and Metalanguage 230
5.5 Research Extensions 233
Bibliography 235

6 Nonmonotonic Reasoning **239**
Gerhard Brewka, Ilkka Niemelä and Mirosław Truszczyński
6.1 Introduction . . . 239
Rules with exceptions . . . 240
The frame problem . . . 240
About this chapter . . . 241
6.2 Default Logic . . . 242
6.2.1 Basic Definitions and Properties . . . 242
6.2.2 Computational Properties . . . 246
6.2.3 Normal Default Theories . . . 249
6.2.4 Closed-World Assumption and Normal Defaults . . . 250
6.2.5 Variants of Default Logic . . . 252
6.3 Autoepistemic Logic . . . 252
6.3.1 Preliminaries, Intuitions and Basic Results . . . 253
6.3.2 Computational Properties . . . 258
6.4 Circumscription . . . 260
6.4.1 Motivation . . . 260
6.4.2 Defining Circumscription . . . 261
6.4.3 Semantics . . . 263
6.4.4 Computational Properties . . . 264
6.4.5 Variants . . . 266
6.5 Nonmonotonic Inference Relations . . . 267
6.5.1 Semantic Specification of Inference Relations . . . 268
6.5.2 Default Conditionals . . . 270
6.5.3 Discussion . . . 272
6.6 Further Issues and Conclusion . . . 272
6.6.1 Relating Default and Autoepistemic Logics . . . 273
6.6.2 Relating Default Logic and Circumscription . . . 275
6.6.3 Further Approaches . . . 276
Acknowledgements . . . 277
Bibliography . . . 277

7 Answer Sets **285**
Michael Gelfond
7.1 Introduction . . . 285
7.2 Syntax and Semantics of Answer Set Prolog . . . 286
7.3 Properties of Logic Programs . . . 292
7.3.1 Consistency of Logic Programs . . . 292
7.3.2 Reasoning Methods for Answer Set Prolog . . . 295
7.3.3 Properties of Entailment . . . 297
7.3.4 Relations between Programs . . . 298
7.4 A Simple Knowledge Base . . . 300
7.5 Reasoning in Dynamic Domains . . . 302
7.6 Extensions of Answer Set Prolog . . . 307
7.7 Conclusion . . . 309
Acknowledgements . . . 310
Bibliography . . . 310

8 Belief Revision **317**
Pavlos Peppas
8.1 Introduction . . . 317
8.2 Preliminaries . . . 318
8.3 The AGM Paradigm . . . 318
8.3.1 The AGM Postulates for Belief Revision . . . 319
8.3.2 The AGM Postulates for Belief Contraction . . . 320
8.3.3 Selection Functions . . . 323
8.3.4 Epistemic Entrenchment . . . 325
8.3.5 System of Spheres . . . 327
8.4 Belief Base Change . . . 329
8.4.1 Belief Base Change Operations . . . 331
8.4.2 Belief Base Change Schemes . . . 332
8.5 Multiple Belief Change . . . 335
8.5.1 Multiple Revision . . . 336
8.5.2 Multiple Contraction . . . 338
8.6 Iterated Revision . . . 340
8.6.1 Iterated Revision with Enriched Epistemic Input . . . 340
8.6.2 Iterated Revision with Simple Epistemic Input . . . 343
8.7 Non-Prioritized Revision . . . 346
8.8 Belief Update . . . 349
8.9 Conclusion . . . 352
Acknowledgements . . . 353
Bibliography . . . 353

9 Qualitative Modeling **361**
Kenneth D. Forbus
9.1 Introduction . . . 361
9.1.1 Key Principles . . . 362
9.1.2 Overview of Basic Qualitative Reasoning . . . 363
9.2 Qualitative Mathematics . . . 365
9.2.1 Quantities . . . 365
9.2.2 Functions and Relationships . . . 369
9.3 Ontology . . . 371
9.3.1 Component Ontologies . . . 372
9.3.2 Process Ontologies . . . 373
9.3.3 Field Ontologies . . . 374
9.4 Causality . . . 374
9.5 Compositional Modeling . . . 376
9.5.1 Model Formulation Algorithms . . . 378
9.6 Qualitative States and Qualitative Simulation . . . 379
9.7 Qualitative Spatial Reasoning . . . 381
9.7.1 Topological Representations . . . 381
9.7.2 Shape, Location, and Orientation Representations . . . 382
9.7.3 Diagrammatic Reasoning . . . 382
9.8 Qualitative Modeling Applications . . . 383

9.8.1 Automating or Assisting Professional Reasoning 383
9.8.2 Education 384
9.8.3 Cognitive Modeling 386
9.9 Frontiers and Resources 387
Bibliography 387

10 Model-based Problem Solving 395
Peter Struss
10.1 Introduction 395
10.2 Tasks 398
10.2.1 Situation Assessment/Diagnosis 398
10.2.2 Test Generation, Measurement Proposal, Diagnosability Analysis 399
10.2.3 Design and Failure-Modes-and-Effects Analysis 401
10.2.4 Proposal of Remedial Actions (Repair, Reconfiguration, Recovery, Therapy) 402
10.2.5 Ingredients of Model-based Problem Solving 402
10.3 Requirements on Modeling 403
10.3.1 Behavior Prediction and Consistency Check 404
10.3.2 Validity of Behavior Modeling 405
10.3.3 Conceptual Modeling 405
10.3.4 (Automated) Model Composition 406
10.3.5 Genericity 406
10.3.6 Appropriate Granularity 407
10.4 Diagnosis 407
10.4.1 Consistency-based Diagnosis with Component-oriented Models 408
10.4.2 Computation of Diagnoses 418
10.4.3 Solution Scope and Limitations of Component-Oriented Diagnosis 422
10.4.4 Diagnosis across Time 423
10.4.5 Abductive Diagnosis 431
10.4.6 Process-Oriented Diagnosis 434
10.4.7 Model-based Diagnosis in Control Engineering 438
10.5 Test and Measurement Proposal, Diagnosability Analysis 438
10.5.1 Test Generation 439
10.5.2 Entropy-based Test Selection 444
10.5.3 Probe Selection 445
10.5.4 Diagnosability Analysis 446
10.6 Remedy Proposal 446
10.6.1 Integration of Diagnosis and Remedy Actions 448
10.6.2 Component-oriented Reconfiguration 450
10.6.3 Process-oriented Therapy Proposal 453
10.7 Other Tasks 454
10.7.1 Configuration and Design 454
10.7.2 Failure-Modes-and-Effects Analysis 456
10.7.3 Debugging and Testing of Software 456

10.8 State and Challenges . . . 458
Acknowledgements . . . 460
Bibliography . . . 460

11 Bayesian Networks 467
Adnan Darwiche
11.1 Introduction . . . 467
11.2 Syntax and Semantics of Bayesian Networks . . . 468
11.2.1 Notational Conventions . . . 468
11.2.2 Probabilistic Beliefs . . . 469
11.2.3 Bayesian Networks . . . 470
11.2.4 Structured Representations of CPTs . . . 471
11.2.5 Reasoning about Independence . . . 471
11.2.6 Dynamic Bayesian Networks . . . 472
11.3 Exact Inference . . . 473
11.3.1 Structure-Based Algorithms . . . 474
11.3.2 Inference with Local (Parametric) Structure . . . 479
11.3.3 Solving MAP and MPE by Search . . . 480
11.3.4 Compiling Bayesian Networks . . . 481
11.3.5 Inference by Reduction to Logic . . . 482
11.3.6 Additional Inference Techniques . . . 484
11.4 Approximate Inference . . . 485
11.4.1 Inference by Stochastic Sampling . . . 485
11.4.2 Inference as Optimization . . . 486
11.5 Constructing Bayesian Networks . . . 489
11.5.1 Knowledge Engineering . . . 489
11.5.2 High-Level Specifications . . . 490
11.5.3 Learning Bayesian Networks . . . 493
11.6 Causality and Intervention . . . 497
Acknowledgements . . . 498
Bibliography . . . 499

II Classes of Knowledge and Specialized Representations 511

12 Temporal Representation and Reasoning 513
Michael Fisher
12.1 Temporal Structures . . . 514
12.1.1 Instants and Durations . . . 514
12.1.2 From Discreteness to Density . . . 515
12.1.3 Granularity Hierarchies . . . 516
12.1.4 Temporal Organisation . . . 517
12.1.5 Moving in Real Time . . . 517
12.1.6 Intervals . . . 518
12.2 Temporal Language . . . 520
12.2.1 Modal Temporal Logic . . . 520
12.2.2 Back to the Future . . . 521
12.2.3 Temporal Arguments and Reified Temporal Logics . . . 521

12.2.4 Operators over Non-discrete Models 522
12.2.5 Intervals 523
12.2.6 Real-Time and Hybrid Temporal Languages 524
12.2.7 Quantification 525
12.2.8 Hybrid Temporal Logic and the Concept of "now" 528
12.3 Temporal Reasoning 528
12.3.1 Proof Systems 529
12.3.2 Automated Deduction 529
12.4 Applications 530
12.4.1 Natural Language 530
12.4.2 Reactive System Specification 531
12.4.3 Theorem-Proving 532
12.4.4 Model Checking 532
12.4.5 PSL/Sugar 534
12.4.6 Temporal Description Logics 534
12.5 Concluding Remarks 535
Acknowledgements 535
Bibliography 535

13 Qualitative Spatial Representation and Reasoning 551
Anthony G. Cohn and Jochen Renz
13.1 Introduction 551
13.1.1 What is Qualitative Spatial Reasoning? 551
13.1.2 Applications of Qualitative Spatial Reasoning 553
13.2 Aspects of Qualitative Spatial Representation 554
13.2.1 Ontology 554
13.2.2 Spatial Relations 556
13.2.3 Mereology 557
13.2.4 Mereotopology 557
13.2.5 Between Mereotopology and Fully Metric Spatial Representation 566
13.2.6 Mereogeometry 570
13.2.7 Spatial Vagueness 571
13.3 Spatial Reasoning 572
13.3.1 Deduction 574
13.3.2 Composition 575
13.3.3 Constraint-based Spatial Reasoning 576
13.3.4 Finding Efficient Reasoning Algorithms 578
13.3.5 Planar Realizability 581
13.4 Reasoning about Spatial Change 581
13.5 Cognitive Validity 582
13.6 Final Remarks 583
Acknowledgements 584
Bibliography 584

14 Physical Reasoning **597**
Ernest Davis
14.1 Architectures . . . 600
14.1.1 Component Analysis . . . 600
14.1.2 Process Model . . . 601
14.2 Domain Theories . . . 602
14.2.1 Rigid Object Kinematics . . . 603
14.2.2 Rigid Object Dynamics . . . 605
14.2.3 Liquids . . . 608
14.3 Abstraction and Multiple Models . . . 611
14.4 Historical and Bibliographical . . . 614
14.4.1 Logic-based Representations . . . 614
14.4.2 Solid Objects: Kinematics . . . 615
14.4.3 Solid Object Dynamics . . . 616
14.4.4 Abstraction and Multiple Models . . . 616
14.4.5 Other . . . 616
14.4.6 Books . . . 617
Bibliography . . . 618

15 Reasoning about Knowledge and Belief **621**
Yoram Moses
15.1 Introduction . . . 621
15.2 The Possible Worlds Model . . . 622
15.2.1 A Language for Knowledge and Belief . . . 622
15.3 Properties of Knowledge . . . 626
15.4 The Knowledge of Groups . . . 628
15.4.1 Common Knowledge . . . 629
15.4.2 Distributed Knowledge . . . 632
15.5 Runs and Systems . . . 633
15.6 Adding Time . . . 635
15.6.1 Common Knowledge and Time . . . 636
15.7 Knowledge-based Behaviors . . . 637
15.7.1 Contexts and Protocols . . . 637
15.7.2 Knowledge-based Programs . . . 639
15.7.3 A Subtle kb Program . . . 641
15.8 Beyond Square One . . . 643
15.9 How to Reason about Knowledge and Belief . . . 644
15.9.1 Concluding Remark . . . 645
Bibliography . . . 645
Further reading . . . 647

16 Situation Calculus **649**
Fangzhen Lin
16.1 Axiomatizations . . . 650
16.2 The Frame, the Ramification and the Qualification Problems . . . 652
16.2.1 The Frame Problem—Reiter's Solution . . . 654
16.2.2 The Ramification Problem and Lin's Solution . . . 657

16.2.3 The Qualification Problem . . . 660
16.3 Reiter's Foundational Axioms and Basic Action Theories . . . 661
16.4 Applications . . . 665
16.5 Concluding Remarks . . . 667
Acknowledgements . . . 667
Bibliography . . . 667

17 Event Calculus 671
Erik T. Mueller
17.1 Introduction . . . 671
17.2 Versions of the Event Calculus . . . 672
17.2.1 Original Event Calculus (OEC) . . . 672
17.2.2 Simplified Event Calculus (SEC) . . . 674
17.2.3 Basic Event Calculus (BEC) . . . 676
17.2.4 Event Calculus (EC) . . . 679
17.2.5 Discrete Event Calculus (DEC) . . . 681
17.2.6 Equivalence of DEC and EC . . . 683
17.2.7 Other Versions . . . 683
17.3 Relationship to other Formalisms . . . 684
17.4 Default Reasoning . . . 684
17.4.1 Circumscription . . . 684
17.4.2 Computing Circumscription . . . 685
17.4.3 Historical Note . . . 686
17.4.4 Negation as Failure . . . 687
17.5 Event Calculus Knowledge Representation . . . 687
17.5.1 Parameters . . . 687
17.5.2 Event Effects . . . 688
17.5.3 Preconditions . . . 689
17.5.4 State Constraints . . . 689
17.5.5 Concurrent Events . . . 690
17.5.6 Triggered Events . . . 691
17.5.7 Continuous Change . . . 692
17.5.8 Nondeterministic Effects . . . 693
17.5.9 Indirect Effects . . . 694
17.5.10 Partially Ordered Events . . . 696
17.6 Action Language $\mathcal{E}$ . . . 697
17.7 Automated Event Calculus Reasoning . . . 699
17.7.1 Prolog . . . 699
17.7.2 Answer Set Programming . . . 700
17.7.3 Satisfiability (SAT) Solving . . . 700
17.7.4 First-Order Logic Automated Theorem Proving . . . 700
17.8 Applications of the Event Calculus . . . 700
Bibliography . . . 701

18 Temporal Action Logics 709
Patrick Doherty and Jonas Kvarnström
18.1 Introduction . . . 709

18.1.1 PMON and TAL 710
18.1.2 Previous Work 711
18.1.3 Chapter Structure 713
18.2 Basic Concepts 713
18.3 TAL Narratives 716
18.3.1 The Russian Airplane Hijack Scenario 717
18.3.2 Narrative Background Specification 718
18.3.3 Narrative Specification 723
18.4 The Relation Between the TAL Languages $\mathcal{L}$(ND) and $\mathcal{L}$(FL) . . 724
18.5 The TAL Surface Language $\mathcal{L}$(ND) 725
18.5.1 Sorts, Terms and Variables 725
18.5.2 Formulas 726
18.5.3 Statements 727
18.6 The TAL Base Language $\mathcal{L}$(FL) 728
18.6.1 Translation from $\mathcal{L}$(ND) to $\mathcal{L}$(FL) 728
18.7 Circumscription and TAL 730
18.8 Representing Ramifications in TAL 735
18.9 Representing Qualifications in TAL 737
18.9.1 Enabling Fluents 738
18.9.2 Strong Qualification 740
18.9.3 Weak Qualification 740
18.9.4 Qualification: Not Only For Actions 741
18.9.5 Ramifications as Qualifications 742
18.10 Action Expressivity in TAL 742
18.11 Concurrent Actions in TAL 744
18.11.1 Independent Concurrent Actions 744
18.11.2 Interacting Concurrent Actions 745
18.11.3 Laws of Interaction 745
18.12 An Application of TAL: TALplanner 747
18.13 Summary 752
Acknowledgements 752
Bibliography 753

19 Nonmonotonic Causal Logic **759**
Hudson Turner
19.1 Fundamentals 762
19.1.1 Finite Domain Propositional Logic 762
19.1.2 Causal Theories 763
19.2 Strong Equivalence 765
19.3 Completion 766
19.4 Expressiveness 768
19.4.1 Nondeterminism: Coin Tossing 768
19.4.2 Implied Action Preconditions: Moving an Object 768
19.4.3 Things that Change by Themselves: Falling Dominos . 769
19.4.4 Things that Tend to Change by Themselves: Pendulum . 769
19.5 High-Level Action Language $\mathcal{C}+$ 770
19.6 Relationship to Default Logic 771

19.7 Causal Theories in Higher-Order Classical Logic 772
19.8 A Logic of Universal Causation 773
Acknowledgement 774
Bibliography 774

III Knowledge Representation in Applications 777

20 Knowledge Representation and Question Answering 779
Marcello Balduccini, Chitta Baral and Yuliya Lierler
20.1 Introduction 779
20.1.1 Role of Knowledge Representation and Reasoning in QA 780
20.1.2 Architectural Overview of QA Systems Using Knowledge Representation and Reasoning 782
20.2 From English to Logical Theories 783
20.3 The COGEX Logic Prover of the LCC QA System 790
20.4 Extracting Relevant Facts from Logical Theories and its Use in the DD QA System about Dynamic Domains and Trips 792
20.4.1 The Overall Architecture of the DD System 793
20.4.2 From Logic Forms to QSR Facts: An Illustration 794
20.4.3 OSR: From QSR Relations to Domain Relations 796
20.4.4 An Early Travel Module of the DD System 798
20.4.5 Other Enhancements to the Travel Module 802
20.5 From Natural Language to Relevant Facts in the ASU QA System 803
20.6 Nutcracker—System for Recognizing Textual Entailment 806
20.7 Mueller's Story Understanding System 810
20.8 Conclusion 813
Acknowledgements 815
Bibliography 815

21 The Semantic Web: Webizing Knowledge Representation 821
Jim Hendler and Frank van Harmelen
21.1 Introduction 821
21.2 The Semantic Web Today 823
21.3 Semantic Web KR Language Design 826
21.3.1 Web Infrastructure 826
21.3.2 Webizing KR 827
21.3.3 Scalability and the Semantic Web 830
21.4 OWL—Defining a Semantic Web KR Language 831
21.5 Semantic Web KR Challenges 836
21.6 Beyond OWL 836
21.7 Conclusion 837
Acknowledgements 837
Bibliography 838

22 Automated Planning 841
Alessandro Cimatti, Marco Pistore and Paolo Traverso
22.1 Introduction 841

22.2 The General Framework . . . 843
22.2.1 Domains . . . 843
22.2.2 Plans and Plan Executions . . . 844
22.2.3 Goals and Problems . . . 845
22.3 Strong Planning under Full Observability . . . 845
22.4 Strong Cyclic Planning under Full Observability . . . 847
22.5 Planning for Temporally Extended Goals under Full Observability 850
22.6 Conformant Planning . . . 857
22.7 Strong Planning under Partial Observability . . . 859
22.8 A Technological Overview . . . 860
22.9 Conclusions . . . 863
Bibliography . . . 864

23 Cognitive Robotics 869
Hector Levesque and Gerhard Lakemeyer
23.1 Introduction . . . 869
23.2 Knowledge Representation for Cognitive Robots . . . 870
23.2.1 Varieties of Actions . . . 871
23.2.2 Sensing . . . 871
23.2.3 Knowledge . . . 872
23.3 Reasoning for Cognitive Robots . . . 873
23.3.1 Projection via Progression and Regression . . . 873
23.3.2 Reasoning in Closed and Open Worlds . . . 875
23.4 High-Level Control for Cognitive Robots . . . 876
23.4.1 Classical Planning . . . 876
23.4.2 High-Level Offline Robot Programming . . . 877
23.4.3 High-Level Online Robot Programming . . . 879
23.5 Conclusion . . . 881
Bibliography . . . 882

24 Multi-Agent Systems 887
Wiebe van der Hoek and Michael Wooldridge
24.1 Introduction . . . 887
24.2 Representing Rational Cognitive States . . . 888
24.2.1 A Logical Toolkit . . . 890
24.2.2 Dynamic Epistemic Logic . . . 891
24.2.3 Cohen and Levesque's Intention Logic . . . 893
24.2.4 Rao and Georgeff's BDI Logics . . . 896
24.2.5 The KARO Framework . . . 899
24.2.6 Discussion . . . 903
24.2.7 Cognitive Agent Logics in Practice . . . 903
24.3 Representing the Strategic Structure of a System . . . 909
24.3.1 Coalition Logic . . . 910
24.3.2 Strategic Temporal Logic: ATL . . . 913
24.3.3 Knowledge in Strategic Temporal Logics: ATEL . . . 916
24.3.4 CL-PC . . . 919
24.3.5 Applications of Strategic Cooperation Logics . . . 920

24.4 Conclusions 920
Bibliography 920

25 Knowledge Engineering 929
Guus Schreiber
25.1 Introduction 929
25.2 Baseline 929
25.3 Tasks and Problem-Solving Methods 930
25.3.1 Two Sample Problem-Solving Methods 930
25.3.2 The Notion of "Knowledge Role" 934
25.3.3 Specification Languages 935
25.4 Ontologies 936
25.4.1 Ontology Specification Languages 937
25.4.2 Types of Ontologies 938
25.4.3 Ontology Engineering 940
25.4.4 Ontologies and Data Models 941
25.5 Knowledge Elicitation Techniques[1] 941
Bibliography 943

Author Index 947

Subject Index 987