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Transformational semantics for Evolving Logic Programs

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March 30, 2007

1 Introduction

Logic programming

Evolving logic programs

2 Transformational semantics for EVOLP

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Logic programming

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2 Transformational semantics for EVOLP

Logic program

```
day ← not night.  
night ← not day.  
play_violin ← day.  
play_piano ← night.
```

Logic program

$day \leftarrow \text{not } night.$
 $night \leftarrow \text{not } day.$
 $play_violin \leftarrow day.$
 $play_piano \leftarrow night.$

Stable models

$M_1 = \{day, play_violin\}$
 $M_2 = \{night, play_piano\}$

Evolving Logic Programs (EVOLP)

- language based on logic programming
- intended for dynamic environments (e.g. multiagent systems)
- syntax is the same as the syntax of logic programs

EVOLP – Example

$$P = \left\{ \begin{array}{l} \textit{write_thesis} \leftarrow \textit{not tired.} \\ \textit{drink_coffee} \leftarrow \textit{tired, not no_coffee.} \\ \textit{buy_coffee} \leftarrow \textit{tired, no_coffee.} \\ \textit{assert(tired)} \leftarrow \textit{write_thesis.} \\ \textit{assert(not tired)} \leftarrow \textit{drink_coffee.} \end{array} \right\}$$

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2			
3			
4			
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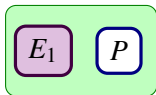
EVOLP – How it works

P

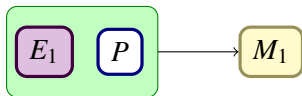
EVOLP – How it works

E_1 P

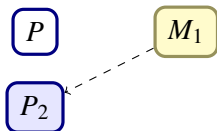
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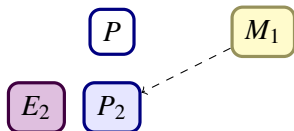


EVOLP – How it works



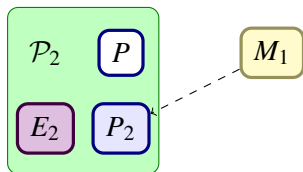
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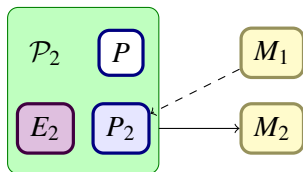
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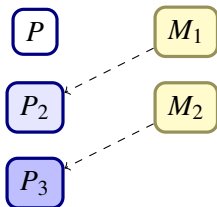
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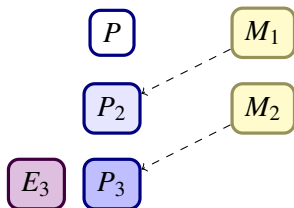
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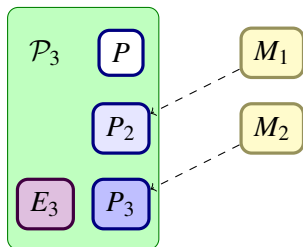
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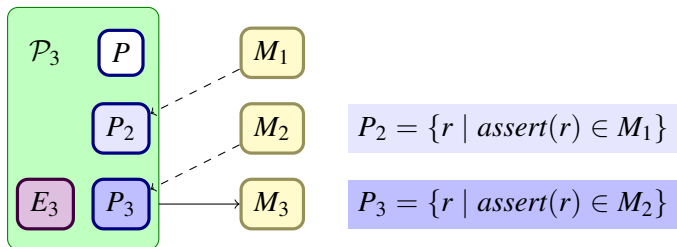
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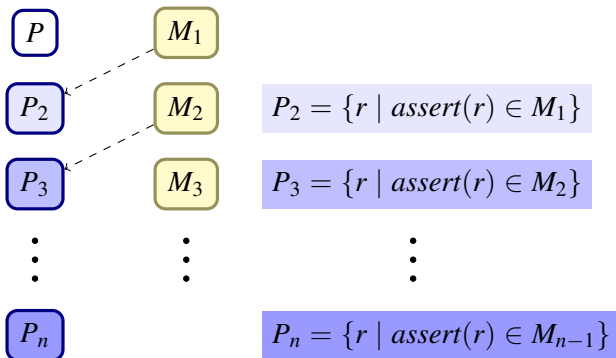
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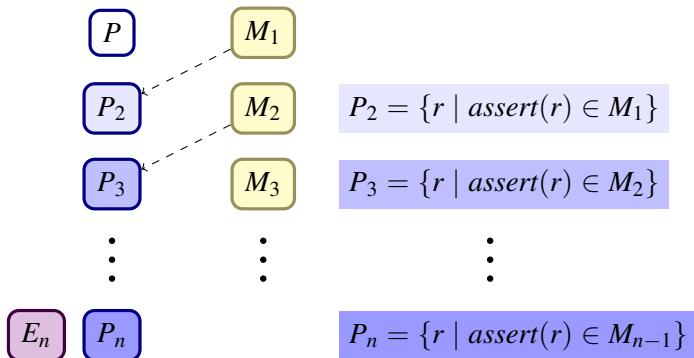
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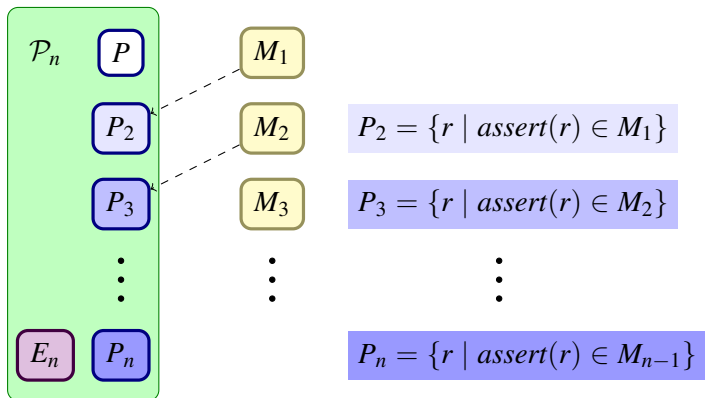
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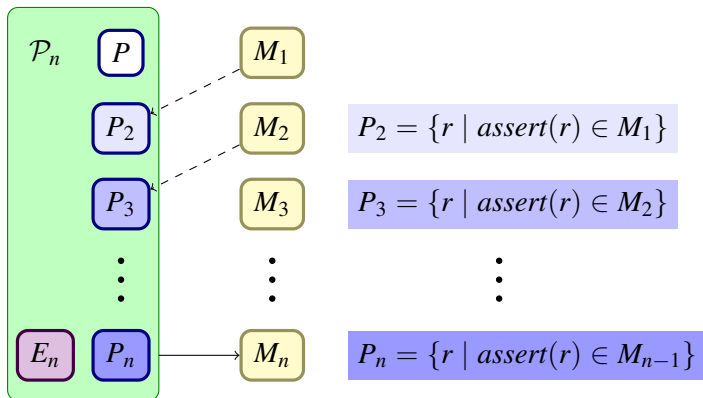
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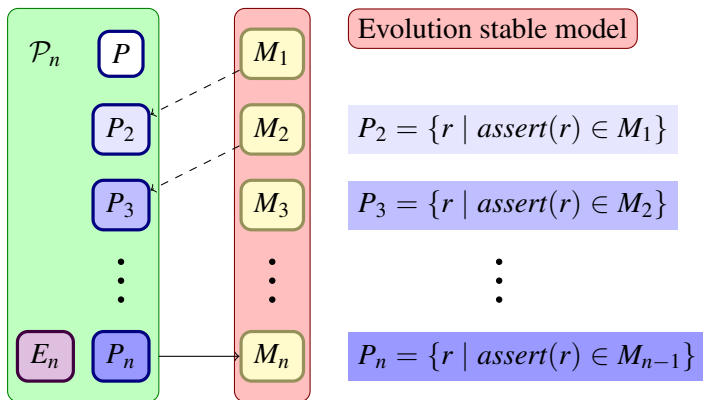
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Transformational semantics for EVOLP

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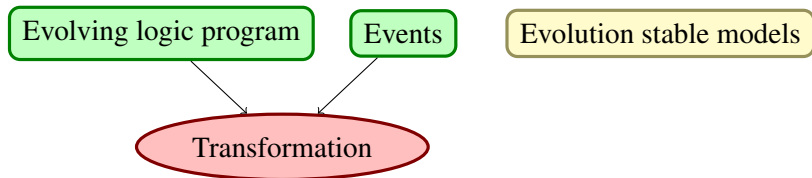
Transformational semantics for EVOLP

Evolving logic program

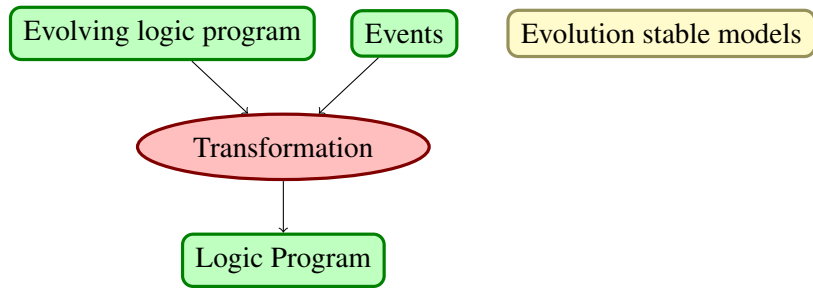
Events

Evolution stable models

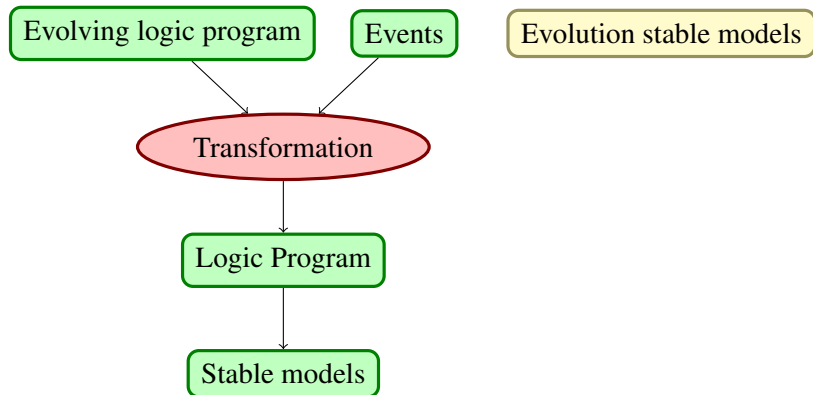
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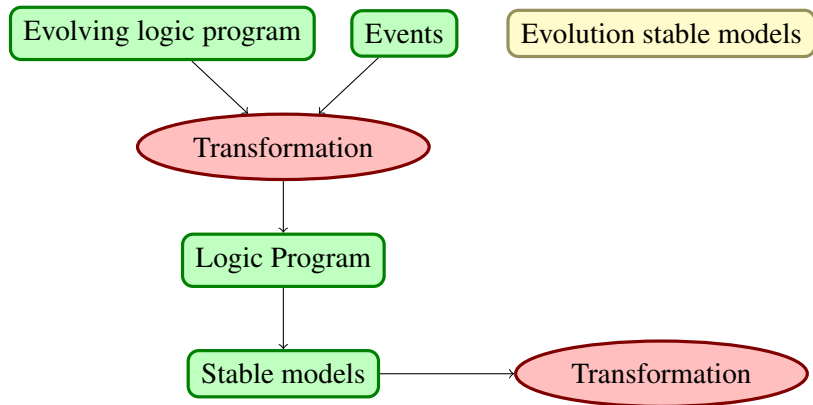
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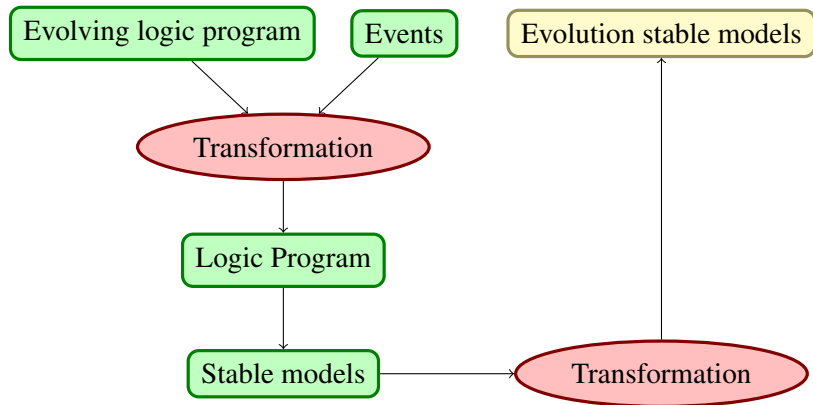
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Transformational semantics for EVOLP



What is all this good for?

- shows that EVOLP can be, in fact, translated into traditional logic programming (and how)
- shows its semantics from a different perspective
- provides a simple, straight-foward way to implement it

Results of the thesis

- definition of the transformation
- proofs of its correctness and completeness
- an implementation of propositional EVOLP

How big is the transformed program?

For an input program P and an event sequence $\mathcal{E} = (E_1, E_2, \dots, E_n)$ over the universe \mathcal{U} we have:

- transformed program is built of $2n|\mathcal{U}|$ atoms (at most)
- lower bound for the size of the transformed program:

$$|P_{\mathcal{E}}| \geq n|P| + \sum_{k=1}^n |E_k|$$

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- upper bound if input programs contain no nested asserts:

$$|P_{\mathcal{E}}| \leq \frac{7}{2} \left(|P| \frac{n^2 + n}{2} + \sum_{k=1}^n |E_k| (n - k + 1) \right) + n|\mathcal{U}|$$

Future work

- extensions of the existing implementation:
 - variable support
 - support for arithmetic predicates
 - ...
- a different, more direct implementation that could be used on-line

Thank you

Thank you.
Are there any questions?